a base;

a video monitor movably mounted to the base for receiving and displaying an image of the remote conferee;

a video camera movably mounted on the base;

control means mounted on the base for moving the video monitor and video camera in response to an input control signal derived from a remote signal generated by the remote conferee; and

wherein said video monitor and video camera move in response to said input control signal to enable the remote conferee to project a sense of presence into the group meeting.

6. (amended) A teleconferencing robot as claimed in claim 1, wherein said input control signal is optionally derived from sound source detection means such that said control signal represents the direction of said sound source with respect to said monitor and said control means being adapted to drive said video monitor, in response to said control signal, to a position substantially facing said detected direction.

Please delete claim 20.

Please insert new claim 21 as follows:

21. (new) A teleconferencing robot, for enabling a remote conferee to project a sense of presence into a group meeting, said remote conferee located remotely from said group meeting, the teleconferencing robot comprising:

a base;

a video monitor movably mounted to the base for receiving and displaying an image of the remote conferee;

a video camera;

control means mounted on the base for moving the video monitor in response to an input control signal derived from a remote signal generated by the remote conferee; and

wherein said video monitor move in response to said input control signal to enable the remote conferee to project a sense of presence into the group meeting.